

Basics

As of ICD version **3.37** (and **PFx Brick** firmware versions **1.40+**), the ability to execute complex actions and behaviours defined in script files was added. Script files are simple, human readable text files stored in the **PFx Brick** file system. These files conform to a simple script language syntax summarized in this cheatsheet.

- Scripts are ASCII text files stored in the PFx Brick file system.
- Scripts execute one at a time. Executing another script will terminate the current script and start the new one.
- Script execution is sequential line-by-line from the start of the file to the end. At the end, the script will either stop or repeat if a repeat command is the last line.

Editing Scrips

Edit script files with the text editor of your choice (e.g. Notepad on Windows, TextEdit on macOS). PFx Language extensions with syntax highlighting for Visual Studio Code and Notepad++ can be found here:

https://github.com/fx-bricks/pfx-brick-vscode https://github.com/Brickelectronic/pfxbrick_notepadplusplus

```
samples > 📔 traffic_light.pfx
      # Ch 4: Don't Walk, Ch 5: Walk
     # reset all light o 1 # Traffic light sequence
      light all off
                              # Ch 1: Red, Ch 2: Yellow, Ch 3: Green
                            4 # Ch 4: Don't Walk. Ch 5: Walk
     light [1,4] on
     light [2,3,5] off f 6 # reset all light channels
                                light all off
                                # Red phase
     # Green phase
                            9 light [1,4] on
     light [1,4] off fac 10 light [2,3,5] off fade 0.2
                           11 wait 8.0
                           12 # Green phase
                               light [1,4] off fade 0.2
```

Loading Scripts

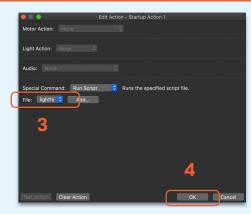


 Drag and drop script file from computer to PFx App Files window

- 2. Click Save Changes to update PFx Brick with new script file
- Select script file from file list and click Test/Run button to run script

Configuring Scripts as Actions





- 1. Select any Remote or Startup action to edit and select Special Command
- 2. Select Run Script from the drop down list
- 3. Select a script file from File drop down list
- 4. Click 0k to confirm

Automatic startup.pfx Script

As of ICD version **3.38** (and **PFx Brick** firmware versions **1.50**+), a special reserved filename "startup.pfx" can be used for a script that you want to automatically launch after power on or reset. This can be useful for setting special configuration or complex startup action sequences.

ICD refers to the Interface Control Document; a document intended for the developer community to build software Apps compatible with the PFx Brick visit our GitHub repo here for more details: https://github.com/fx-bricks/pfx-brick-dev



Syntax Basics

Comments

start with # or //
Valid comment
// Another valid comment
light 1 on # not a valid comment



cannot appear on a line with a command

Numbers

Decimal values

0 127 -55 0.010 35.75 -90.5

Hexadecimal values

0x0 0xABCD 0x32

Lists

[0, 5, 8] enclose in [] comma"," separated

Strings

"This is a string" enclose in " "double quotes

Keyword Commands

Keyword commands appear at the beginning of a line followed by other keywords and values depending on the command syntax.

event motor set wait ir repeat sound light run stop

Other Keywords

Other keywords are used in support of commands as qualifiers or arguments.

confia invert acc servo all connect joy shutdown left bass decel speed disconnect loop beep startup ble down long thr treble brake fade off briaht file on up flash button play usb vol ch fx rate changedir gated right



all keywords must be separated by whitespace

Run/Stop Commands

execute another script

run file file : file ID number or string
run "traffic_light"

stop execution

stop

wait 3.5

Wait Command

wait for time delay

wait for sound file playback end

wait sound file file: file ID number or string
wait for sound file 2 to stop
wait sound 2
wait for "Siren1.wav" to stop
wait sound "Siren1.wav"

wait for IR event

wait ir parameters

parameters : any combination of:
joy : joystick remote
speed : speed control remote
up, down, left, right, button : remote actions
ch value : IR channel (1, 2, 3, 4)

wait for the joystick left control
pushed up on any IR channel
wait ir joy left up
wait for the left button on speed remote
on IR channel 4
wait ir speed ch 4 left button

wait for pushbutton event (from touchLAB)

wait button

wait for button press
wait button

Repeat Command

repeat current script from start

repeat restarts the script from the beginning

repeat enclosed code block (with nesting)

```
repeat count { repeats a block of code count number of times enclosed in braces { }
```



opening { must be on same line as repeat closing } must be on a line by itself

```
# repeat this code 5 times
repeat 5 {
    light 1 on
    wait 2.0
    light 1 off
    wait 10
}

# nested repeats
repeat 5 {
    light 1 fx 1
    repeat 3 {
        light 2 fx 1
        wait 2.0
    }
}
```

IR Command

ir on activate IR sensor
ir off disables IR sensor

Sound Command

sound command

Commands

```
simple playback
```

play file
sound play 3
sound play "Siren1.wav"

continously repeated playback

play file repeat
sound play 3 repeat
sound play "Siren1.wav" repeat

playback a number of times

random playback

stop playback

stop file file: file ID number, string, or all
sound stop 3
sound stop "Siren1.wav"
sound stop all

set volume

vol value value : 0 – 255

sound vol 0

set bass / treble

bass value treble value value:-20 - +20
sound bass 3

short beep sound

beep

sound beep

Light Command

light channels commands

Channels

light 1 single channel
light [2, 4, 5] multiple channels
light all all channels

Commands

simple on/off

on off
light 1 on
light [1, 2, 4] off
light all off

flashing light

flash ontime offtime

ontime, offtime: 0.05 – 60 seconds offtime is optional; if omitted ontime=offtime

on for 0.5 sec, off for 0.5 sec light 1 flash 0.5 # on for 0.1 sec, off for 0.4 sec light [1, 2, 4] flash 0.1 0.4

optional fade

fade time time: 0 - 10 seconds

combine with on, off, & flash commands

fade channel 1 on
light 1 on fade 0.5
fade channels 3, 5 off
light [3, 5] off fade 1.0
1.5 sec flash with 0.2 sec fade
light 8 flash 1.5 fade 0.2

set brightness

bright value value: 0 – 255

channel brightness 10
light 1 bright 10
channels 1,2,4 brightness 255
light [1, 2, 4] bright 255

Motor Command

motor channels commands

Channels

motor a single channel
motor [a, b] multiple channels
motor all all channels

Commands

set speed

speed value value:-255 - +255
motor a speed -50
motor all speed 100

stop

motor b stop
motor all stop

servo angle

servo value value: -90 – +90

motor a servo -90

optional acceleration/deceleration momentum

acc rate rate: 0-15

combine with **speed** & **stop** commands

accelate motor b to half speed gradually
motor b speed 128 acc 12
stop motor a with gentle slow down
motor a stop acc 8



Event Command

event event { stores actions enclosed in braces { } associated to specified events



opening { must be on same line as **event** closing } must be on a line by itself

Actions specified between braces are **not** performed during script execution. They are stored in the PFx Brick's non-volatile memory and executed when the desired event occurs.

Multiple actions can be associated with an event. However, only **one** of each type can be stored, similar to how actions are configured in the PFx App.



The follow actions are not supported with event

sound bass wait light flash sound treble set sound beep repeat



event cannot be used inside a **repeat** block

Events

event can be specified in the following ways:

Event Numeric Address

consult the ICD documentation for event LUT address details

Startup Events

```
# store sound action to startup event 3
event startup 3 {
   sound play "Siren1.wav"
}
```

IR Event

```
event ir parameters {
  parameters : any combination of:
  joy : joystick remote
  speed : speed control remote
  up, down, left, right, button : remote actions
  ch value : IR channel (1, 2, 3, 4)

# store sound action when joystick
# left stick is pushed up on ch 1
  event ir joy left up ch 1 {
    sound play "Beep.wav"
}
```

Special Events

```
event button {
                        button press
event button long {
                        long button press
event button down {
                        button down
event button up {
                        button up
event ble connect {
                        Bluetooth host connect
event ble disconnect { BLE host disconnected
event usb connect {
                        USB host connect
event usb disconnect { USB host disconnected
# light action when button is pressed
event button {
  light all on
```

```
light all on
}

# define sound action and disable IR
# when a Bluetooth host establishes
# a connection
event ble connect {
    sound play "Welcome.wav"
    ir off
}
# define sound action and enable IR
# when a Bluetooth host disconnects
event ble disconnect {
    sound play "Goodbye.wav"
    ir on
}
```

The **event** command is useful for making configuration scripts which can be executed as a startup action. This is an alternative to using the PFx App to define the brick's configuration.

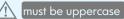
Set Command

variables

set var = value

There are 6x variable registers called:

\$A, \$B, \$C, \$D, \$E, \$F



Both numeric and string values can be stored with the **set** command and can represent values in other commands

```
set $A = 50
motor a speed $A

set $A = 1.5
set $F = 0.1
light [1, 2] flash $A fade $F
set $B = "LongBeep.wav"
sound play $B
wait sound $B
```

configuration

set config var = value



var must be lowercase

var	value	ch	Description
<pre>set config bass = value set config treble = value set config vol = value set config bright ch = value</pre>	-20 - +20 -20 - +20 0 - 255 0 - 255		Audio bass Audio treble Default volume Default brightness
<pre>set config nc = value set config nb ch = value</pre>	1 - 8 0 - 255	1 - 8	Notch count for indexed sound Speed between notch boundaries
<pre>set config motor ch accel = value set config motor ch decel = value set config motor ch invert = value set config motor ch v0 = value set config motor ch v1 = value set config motor ch v2 = value</pre>	0 - 15 0 - 15 0 - 1 0 - 255 0 - 255 0 - 255	a, b a, b a, b a, b a, b	Motor acceleration Motor deceleration Invert motor polarity Speed curve min speed Speed curve mid speed Speed curve max speed
<pre>set config thr accel = value set config thr decel = value set config thr rate = value set config thr speed = value</pre>	0 - 255 0 - 255 0 - 255 0 - 255		Thr for rapid accel sound Thr for rapid decel sound Thr accel braking sound Thr speed for braking sound

file attributes

set file type = file

Audio files used for motor indexed playback and gated playback based on motor speed can be assigned in a script.

		type		ch	
set	file	speed ch =	file	1 - 8	
set	file	<pre>accel ch =</pre>	file	1 - 7	
set	file	decel ch =	file	1 - 7	
set	file	<pre>gated ch =</pre>	file	11-14, 31-34,	
set	file	startup = f	file	31 31,	
		shutdown =			
set	file	changedir =	file		
		thr accel =			
set	file	thr decel =	= file		
set	file	brake on =	file		
set	file	brake off =	= file		

<u>^</u>

type must be lowercase

file can be specified with either a numeric file ID or filename string.

Description

Sound loop at speed notch

Sound loop for accel between notches

Sound loop for decel between notches

Gated sound loops (4x for ea. notch 1-4)

Sound played at startup
Sound played for shutdown
Sound played due to direction change
Sound played with rapid accel
Sound played due to rapid decel
Sound played with brake application
Sound played at set-off from stop

values changed with **set config** replace existing configuration settings in the PFx Brick non-volatile memory

set number of notch levels to 4
set config nc = 4
set config nb 1 = 60
set default volume to 80
set config vol = 80
set motor parameters
set config motor a accel = 4
set config motor a invert = 1

file assignments made with **set file** will modify the file directory entry on PFx Brick file system

set file startup = "EngineStart.wav"
set file speed 1 = "IdleLoop1.wav"
set file accel 1 = 250
set file accel 12 = "ChuffLoop12.wav"

Fx Commands

Commands using the **fx** keyword are used for activating the advanced builtin effects

light channels fx id parameters
light all fx id parameters
motor channels fx id parameters
sound fx id file parameters

An effect is specified by a numeric *id* value. Zero of more *parameters* are appended to the command if required. Parameter values follow immediately separated by spaces or in a list.

```
# Equally valid syntaxes for fx parameters
# Parameters after
light all fx 2 4 3 0 1
# Parameters in a list
light all fx 2 [4, 3, 0, 1]
```

Each Fx type has its own number of parameters. The number of parameters and their respective definitions are shown in the diagrams over the next few pages.

This example shows a light Fx command and its corresponding details for each parameter

Param 1

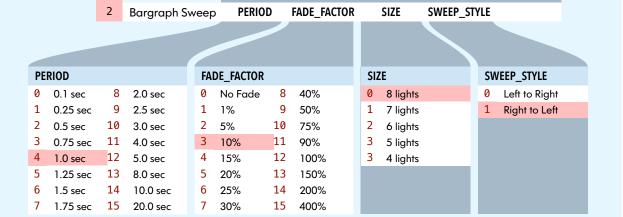
```
# Bargraph Sweep
# Right to Left
# 1 sec period, 10% fade, 8 lights
light all fx 2 4 3 0 1
```

Param 2

Param 3

Param 4

Param 5



Effect Name

Light Fx Command

lig	nt channels fx id paramete	ers (up to	5 parameters)										
id	Effect Name	Param 1	Param 2	Param 3		DIR_OPTION				SOUR	CE1		SO	URCE2
1	On/Off with options	DIR_OPTION	FADE_TIME	FLICKER_ON	7	0 None		dd if A ▲ Even				Connected		01 Motor A ▲
2	Increase Brightness					1 On if A ▲ 1						Activity		02 Motor A ▼
3	Decrease Brightness					2 On if A ▼ 1 3 On if B ▲ 1						ctivity ockout active		04 Motor B ▲ 08 Motor B ▼
4	Set Brightness	BRIGHTNESS				4 On if B ▼ 1						io active		10 -
5	50% Flasher (positive)	PERIOD	FADE_FACTOR			5 On if C ▲ 1						Connected		20 -
6	50% Flasher (negative)	PERIOD	FADE FACTOR			6 On if C ▼ 1	. 5 O	dd if C ▼ Even	if C			Activity	0x	40 Button
7	Strobe Flasher (positive)	PERIOD	DUTY CYCLE	BURST COUNT		7 On if D ▲ 1	. <mark>6</mark> O	dd if D ▼ Even	if D	▲ 0x80	Files	system active	0x	80 -
8	Strobe Flasher (negative)	PERIOD	DUTY_CYCLE	BURST_COUNT		8 On if D ▼					lo	gic OR combo		logic OR combo
9	Gyralite Flasher (positive)	PERIOD	FADE_FACTOR	201131_COON1		PERIOD			F	ERIOD2			FLI	CKER_ON
10	Gyralite Flasher (negative)	PERIOD	FADE_FACTOR			0 0.1 sec	8	2.0 sec	0	0.05 sec	8	0.8 sec	0	No
11	Flicker	PERIOD2	FADE_FACTOR			1 0.25 sec	9	2.5 sec	1	0.1 sec	9	0.9 sec	1	Yes
12	Random Blinker	PERIOD2	FADE_FACTOR			2 0.5 sec	10	3.0 sec	2	0.2 sec	10	1.0 sec		
13	Photon Torpedo	PERIOD2				3 0.75 sec	11	4.0 sec	3		11			RST_COUNT
14	Laser Pulse	PERIOD2				4 1.0 sec	12	5.0 sec	4		12		0	1 pulse
15	Engine Glow	PERIOD				5 1.25 sec 6 1.5 sec	13 14	8.0 sec 10.0 sec	5		13 14	1.75 sec 2.0 sec	2	2 pulses 3 pulses
16	Lighthouse	PERIOD				7 1.75 sec	15	20.0 sec	7		15		3	4 pulses
17	_	FAULT_RATE	FADE_TIME	FAULT_INTENSITY				20.0 000				0.0 000		. poses
18	Broken Light Status Indicator	SOURCE1	SOURCE2	INVERT		FADE_TIME			F	ADE_FACTOR			IN	VERT
			SOURCEZ	INVERT		0 No Fade	8	1.0 sec	0		8	40%	0	No
19	Sound Modulated	FADE_TIME	COLIDORA			1 50 ms	9	1.5 sec	1		9	50%	1	Yes
20	Motor Speed Modulated	FADE_TIME	SOURCE2	INVERT		2 0.1 sec 3 0.2 sec	10 11	2.0 sec 2.5 sec	3		10 11	75% 90%	FΔI	ULT_RATE
		Param 4		Param 5		4 0.4 sec	12	2.5 sec 3.0 sec	4		12	100%	0	Rare
XX	All Effects			RGB		5 0.5 sec	13	4.0 sec	5		13	150%	1	Occasionally
	7 6 5 4	3 2 1 0				6 0.6 sec	14	5.0 sec	6	25%	14	200%	2	Often
		ХХ		RGB		7 0.8 sec	15	10.0 sec	7	30%	15	400%	3	Very Often
				0 White		DUTY CYCLE							FA	III INTENCITY
	DURATION	TRANSITION		1 Red		DUTY_CYCLE	_	000/	10	(00)	1 5	000/		ULT_INTENSITY
	0 0.5 sec 8 15 sec	0 Toggle		2 Green 3 Blue		0 1% 1 2%	5 6	20% 25%	10 11	60% 70%	15 16	90% 95%	0	Subtle Moderate
	1 1.0 sec 9 20 sec 2 1.5 sec 10 30 sec	1 On 2 Off		3 Blue 4 Cyan		2 5%	7	30%	12	75%	17	98%	2	Severe
	2 1.5 sec 10 30 sec 3 2.0 sec 11 45 sec		URATION	5 Magenta		3 10%	8	40%	13	80%	18	99%	3	Maximum
	4 3.0 sec 12 60 sec	Sirioi E	Challon	6 Yellow		4 15%	9	50%	14	85%				
	5 4.0 sec 13 90 sec			7 Orange										
	6 5.0 sec 14 2 min			8 Turquoise										
	7 10 sec 15 5 min			9 Violet										

Light Combo Fx Command

ι	igh	t all fx id parameters	(up to 5 paran	neters)			
i	id	Effect Name	Param 1	Param 2	Param 3	Param 4	Param 5
	1	Linear Sweep	PERIOD	FADE_FACTOR	SIZE	SWEEP_STYLE	
	2	Bargraph Sweep	PERIOD	FADE_FACTOR	SIZE	SWEEP_STYLE	
	3	Knight Rider	PERIOD	FADE_FACTOR			
	4	Emergency Flasher (Twinsonic)	TWIN_STYLE	SEQ	FLASH_RATE		
	5	Emergency Flasher (Whelen)	WHELEN_STYLE	SEQ	FLASH_RATE		
	6	Times Square	PERIOD2	FADE_FACTOR			
	7	Noise	PERIOD2	FADE_FACTOR			
	8	Twinkling Stars	PERIOD	DUTY_CYCLE			
	9	Traffic Lights	TRAFFIC_STYLE	FADE_FACTOR	SEQ_TIME		
	10	Sound Bar	BAR_STYLE	FADE_FACTOR	SIZE		
:	11	Alternating Flashers	PERIOD	FADE_FACTOR	DUTY_CYCLE	OUT_MASK	TRANSITION
	12	Lava Lamp	PERIOD	SIZE			
	13	Laser Cannon	FLASH_RATE	FADE_FACTOR	SIZE	SWEEP_STYLE	
	14	Dragster Starter	DRAGSTER_STYLE	FADE_FACTOR			
:	15	Airport Runway	RUNWAY_RATE	FADE_FACTOR	RUNWAY_BRIGHT		
	16	Formula 1 Indicators	F1_STYLE	FADE_FACTOR	FLASH_RATE		

TRAFFIC_STYLE	WHELEN_STYLE				DRAGSTER_STYLE				
Standard		0	Sign	al Alert		0 Stand	dar	d countdown to green	
1 Standard with flash	ng green	1	Sign	al Alert Steady		1 Pro c	our	ntdown (0.5 sec)	
2 European		2	Com	et Flash		2 Pro c	our	ntdown (0.4 sec)	
3 Flash red (NS), flash	yellow (EW)	3	Actio	on Flash 50					
4 Standard w/ped cr	ossing	4	Actio	on Flash 150		F1_STYLE			
5 European w/ped cr	ossing	5	Mod	u Flash		Race	stc	ırt countdown	
6 Flash red (EW), flash yellow (NS)			Sing	Single Flash 1 Trainir			ning countdown		
7 International		7	7 Double Flash			2 Race break/caution			
8 International w/ped	d crossing	8	8 Triple Flash			3 Training start			
9 International 2		9 Warning			4 Training break				
10 International 2 w/p	ed crossing	10	Rand	dom		5 Train	ing	end	
RUNWAY_RATE	RUNWAY B	DICHT		OUT MASK loo	nic C)P combo		TRANSITION	
_	_			= '					
aready (ine masiming)		um		0x01 Ch 1 (0 Toggle	
1 Slow	1 Med		0x02 Ch 2					1 to On	
² Med	2 Low			0x04 Ch 3 ()x4	10 Ch 7		2 to Off	
3 Fast 3 Minimu				0x08 Ch 4	3x6	30 Ch 8		3 Duration	

''-	RIOD		SWEEP_STYLE	
0	0.1 sec	8	2.0 sec	0 Left to Right
1	0.25 sec	9	2.5 sec	1 Right to Left
2	0.5 sec	10	3.0 sec	
3	0.75 sec	11	4.0 sec	FLASH_RATE
4	1.0 sec	12	5.0 sec	Slow (60 fpm)
5	1.25 sec	13	8.0 sec	1 Med (90 fpm)
6	1.5 sec	14	10.0 sec	2 Fast (120 fpm)
7	1.75 sec	15	20.0 sec	3 V. Fast (150 fpm)
DE	DIOD2			CITE
	RIOD2	0	0.0	SIZE
0	0.05 sec	8	0.8 sec	0 8 lights
1	0.1 sec	9	0.9 sec	1 7 lights
2	0.2 sec	10	1.0 sec	2 6 lights
3	0.3 sec	11	1.25 sec	3 5 lights
4	0.4 sec	12	1.5 sec	3 4 lights
5	0.5 sec	13	1.75 sec	SEQ
6	0.6 sec	14	2.0 sec	
7	0.7 sec	15	3.0 sec	
FΛ	DE_FACTOR			1 Left/Right 1 In/Out
	_			1 III/O01
a	No Lado	×	10°/	
0	No Fade	8 9	40%	SEQ TIME
1	1%	9	50%	SEQ_TIME Slow (60 sec)
1 2	1% 5%	9 10	50% 75%	0 Slow (60 sec)
1 2 3	1% 5% 10%	9 10 11	50% 75% 90%	Slow (60 sec)Med (45 sec)
1 2 3 4	1% 5% 10% 15%	9 10 11 12	50% 75% 90% 100%	Slow (60 sec)Med (45 sec)Fast (30 sec)
1 2 3 4 5	1% 5% 10% 15% 20%	9 10 11 12 13	50% 75% 90% 100% 150%	Slow (60 sec)Med (45 sec)
1 2 3 4	1% 5% 10% 15%	9 10 11 12	50% 75% 90% 100%	Slow (60 sec)Med (45 sec)Fast (30 sec)
1 2 3 4 5 6	1% 5% 10% 15% 20% 25%	9 10 11 12 13 14	50% 75% 90% 100% 150% 200%	0 Slow (60 sec)1 Med (45 sec)2 Fast (30 sec)3 Very Fast (20 sec)
1 2 3 4 5 6 7	1% 5% 10% 15% 20% 25%	9 10 11 12 13 14	50% 75% 90% 100% 150% 200%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE
1 2 3 4 5 6 7	1% 5% 10% 15% 20% 25% 30%	9 10 11 12 13 14	50% 75% 90% 100% 150% 200%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero
1 2 3 4 5 6 7	1% 5% 10% 15% 20% 25% 30%	9 10 11 12 13 14 15	50% 75% 90% 100% 150% 200% 400%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual
1 2 3 4 5 6 7	1% 5% 10% 15% 20% 25% 30%	9 10 11 12 13 14 15	50% 75% 90% 100% 150% 200% 400%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero Combo
1 2 3 4 5 6 7	1% 5% 10% 15% 20% 25% 30% OTY_CYCLE 1% 2%	9 10 11 12 13 14 15	50% 75% 90% 100% 150% 200% 400%	0 Slow (60 sec) 1 Med (45 sec) 2 Fast (30 sec) 3 Very Fast (20 sec) TWINSONIC_STYLE 0 Single 1 Dual 2 Aero 3 Combo BAR_STYLE
1 2 3 4 5 6 7 DU 0 1 2	1% 5% 10% 15% 20% 25% 30% ITY_CYCLE 1% 2% 5%	9 10 11 12 13 14 15	50% 75% 90% 100% 150% 200% 400%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero Combo BAR_STYLE Left to Right
1 2 3 4 5 6 7 DUU 0 1 2 3	1% 5% 10% 15% 20% 25% 30% ITY_CYCLE 1% 2% 5% 10%	9 10 11 12 13 14 15 10 11 12 13	50% 75% 90% 100% 150% 200% 400% 60% 70% 75% 80%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero Combo BAR_STYLE Left to Right Right to Left
1 2 3 4 5 6 7 DU 0 1 2 3 4	1% 5% 10% 15% 20% 25% 30% ITY_CYCLE 1% 2% 5% 10% 15%	9 10 11 12 13 14 15 10 11 12 13 14	50% 75% 90% 100% 150% 200% 400% 60% 70% 75% 80% 85%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero Combo BAR_STYLE Left to Right Right to Left In to Out
1 2 3 4 5 6 7 DU 0 1 2 3 4 5	1% 5% 10% 15% 20% 25% 30% ITY_CYCLE 1% 2% 5% 10% 15% 20%	9 10 11 12 13 14 15 10 11 12 13 14 15	50% 75% 90% 100% 150% 200% 400% 60% 70% 75% 80% 85% 90%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero Combo BAR_STYLE Left to Right Right to Left
1 2 3 4 5 6 7 DUU 0 1 2 3 4 5 6	1% 5% 10% 15% 20% 25% 30% ITY_CYCLE 1% 2% 5% 10% 15% 20% 25%	9 10 11 12 13 14 15 10 11 12 13 14 15 16	50% 75% 90% 100% 150% 200% 400% 60% 70% 75% 80% 85% 90% 95%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero Combo BAR_STYLE Left to Right Right to Left In to Out
1 2 3 4 5 6 7 DU 0 1 2 3 4 5 6 7 7	1% 5% 10% 15% 20% 25% 30% ITY_CYCLE 1% 2% 5% 10% 15% 20% 25% 30%	9 10 11 12 13 14 15 10 11 12 13 14 15 16 17	50% 75% 90% 100% 150% 200% 400% 60% 70% 75% 80% 85% 90% 95% 98%	 Slow (60 sec) Med (45 sec) Fast (30 sec) Very Fast (20 sec) TWINSONIC_STYLE Single Dual Aero Combo BAR_STYLE Left to Right Right to Left In to Out

Motor Fx Command

motor channels fx id parameters

(up to 2 parameters)

id	Effect Name	Param 1	Param 2
0	Emergency Stop		
1	Stop		
2	Increase Speed	MOTOR_STEP	
3	Decrease Speed	MOTOR_STEP	
4	Increase Speed (Bidirectional)	MOTOR_STEP	
5	Decrease Speed (Bidirectional)	MOTOR_STEP	
6	Change Direction		
7	Set Speed	MOTOR_SPEED	
8	Set Speed (Timed duration)	MOTOR_SPEED	DURATION
9	Oscillate	MOTOR_SPEED	MOTOR_PERIOD
10	Oscillate Bidirectional	MOTOR_SPEED	MOTOR_PERIOD
11	Oscillate Bidirectional with Wait	MOTOR_SPEED	MOTOR_PERIOD
12	Random	MOTOR_SPEED	MOTOR_PERIOD
13	Random Bidirectional	MOTOR_SPEED	MOTOR_PERIOD
14	Sound Modulated	MOTOR_SPEED	
15	Set Servo	MOTOR_POS	

MOTOR_STEP													
1 1% (100 steps) 2 2% (50 steps) 3 3% (33 steps) 4 5% (20 steps) 5 6% (16 steps) 6 10% (10 steps) 7 20% (5 steps) 8 25% (4 steps) 9 33% (3 steps) 10 LEGO compatible 7 steps 11 15 deg (servo increment) MOTOR_PERIOD MOTOR_PERIOD 0 0.25 sec 8 3.0 sec 1 0.5 sec 9 4.0 sec 1 0.5 sec 9 4.0 sec 1 1 0.5 sec 1 2.5 sec 1 2.5 sec 5 1.5 sec 1 3 20 sec 6 2.0 sec 1 4 30 sec 7 2.5 sec 1 5 60 sec MOTOR_POS MOTOR_POS 0 -90 deg 7 15 deg 1 -75 deg 8 30 deg 2 -60 deg 9 45 deg 3 -45 deg 10 60 deg DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 90 deg 6 0 deg DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 90 deg 6 0 deg DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 90 sec 11 0.5 sec 9 20 sec 13 90 sec 12 15 sec 15 60 sec 10 30 sec 14 20 sec 15 10 sec 14 30 sec 7 2.5 sec 15 60 sec 10 5.0 sec 11 10 sec 4 1.25 sec 12 15 sec 5 1.5 sec 13 20 sec 5 1.5 sec 6 5.0 sec 10 30 sec 14 20 sec 5 1.5 sec 13 20 sec 5 1.5 sec 13 20 sec 5 1.5 sec 13 20 sec 10 5.0 sec 10 30 sec 11 10 sec 4 1.25 sec 12 15 sec 5 1.5 sec 13 20 sec 5 1.5 sec 13 20 sec 5 1.5 sec 13 20 sec 10 5.0 sec 11 10 sec 4 1.25 sec 12 15 sec 13 20 sec 5 1.5 sec 13 20 sec 5 1.5 sec 13 20 sec 14 30 sec 7 2.5 sec 15 60 sec 7 2.5 se	MC	OTOR_STEP				MOT	OR_SPEED	1					
2 2% (50 steps) 3 3% (33 steps) 4 5% (20 steps) 5 6% (16 steps) 6 10% (10 steps) 7 20% (5 steps) 8 25% (4 steps) 9 33% (3 steps) 10 LEGO compatible 7 steps 11 15 deg (servo increment) MOTOR_PERIOD MOTOR_PERIOD MOTOR_PERIOD MOTOR_POS 0 0.25 sec 8 3.0 sec 1 0.5 sec 9 4.0 sec 2 0.75 sec 10 5.0 sec 3 1.0 sec 11 10 sec 4 1.25 sec 12 15 sec 5 15.5 sec 13 20 sec 6 2.0 sec 14 30 sec 7 2.5 sec 15 60 sec MOTOR_PERIOD MOTOR_POS 0 0.25 sec 8 3.0 deg 1 -75 deg 8 30 deg 2 -60 deg 9 45 deg 3 -45 deg 10 60 deg 4 -30 deg 11 75 deg 5 -15 deg 12 90 deg 6 0 deg DURATION 0 0.5 sec 4 3.0 sec 1 1.0 sec 5 4.0 sec 9 20 sec 13 90 sec 2 1.5 sec 6 5.0 sec 8 15 sec 2 10.5 sec 9 4.0 sec 9 20 sec 14 30 sec 7 2.5 sec 15 60 sec DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 60 sec 10 30 sec 14 2 min	(0 ±1 step	(high r	res)				Low	Resolution 8 S	peed	Step Range)	
3 3% (33 steps) 4 5% (20 steps) 5 6% (16 steps) 6 10% (10 steps) 7 20% (5 steps) 8 25% (4 steps) 9 33% (3 steps) 10 LEGO compatible 7 steps 11 15 deg (servo increment) MOTOR_PERIOD 0 0.25 sec 8 3.0 sec 1 0.5 sec 9 4.0 sec 2 0.75 sec 10 5.0 sec 3 1.0 sec 11 10 sec 4 1.25 sec 12 15 sec 5 1.5 sec 13 20 sec 6 2.0 sec 14 30 sec 7 2.5 sec 15 60 sec MOTOR_PERIOD MOTOR_POS 0 -90 deg 7 15 deg 1 -75 deg 3 -45 deg 1 0 60 deg 4 -30 deg 11 75 deg 5 -15 deg 12 90 deg 6 0 deg DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 60 sec 1 1.0 sec 5 4.0 sec 9 20 sec 14 30 sec 7 2.5 sec 6 5.0 sec 1 30 sec 1 1.0 sec 5 4.0 sec 9 20 sec 14 30 sec 7 2.5 sec 6 5.0 sec 10 30 sec 1 3.0 sec 11 10 sec 4 1.25 sec 12 15 sec 5 1.5 sec 13 20 sec 6 2.0 sec 14 30 sec 7 2.5 sec 15 60 sec DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 60 sec 1 1.0 sec 5 4.0 sec 9 20 sec 13 90 sec 2 1.5 sec 6 5.0 sec 10 30 sec 14 2 min	:	1 1% (100	steps))		0	stopped			8	stopped		
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5 6% (16 steps) 4 50% speed in the 12 50% speed in the 6 10% (10 steps) 6 75% forward direction 13 67% reverse direction 7 20% (5 steps) 6 75% 14 75% 8 25% (4 steps) 7 100% 15 100% 9 33% (3 steps) High Resolution 64 Speed Step Range 10 LEGO compatible 7 steps 11 15 deg (servo increment) 11 15 deg (servo increment) 128 stopped 129 1 193 1 130 2 194 2 10 0.25 sec 8 3.0 sec 190 62 2 0.75 sec 10 5.0 sec 190 62 3 1.0 sec 11 10 sec 190 62 4 1.25 sec 12 15 sec 191 63 5 1.5 sec 13 20 sec 6 2.0 sec 14 30 sec 6 2.0 sec 14 30 sec Off Time Off Time Off Time OFF TIME MOTOR_PERIOD Direction OFF TIME OFF TIME OFF TIME ON TIME OFF TIME OFF TIME OFF T		•				2	25%			10	25%		
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7 20% (5 steps) 8 25% (4 steps) 9 33% (3 steps) 10 LEGO compatible 7 steps 11 15 deg (servo increment) MOTOR_PERIOD 0 0.25 sec 8 3.0 sec 1 0.5 sec 9 4.0 sec 2 0.75 sec 10 5.0 sec 3 1.0 sec 11 10 sec 4 1.25 sec 12 15 sec 5 1.5 sec 13 20 sec 6 2.0 sec 14 30 sec 7 2.5 sec 15 60 sec MOTOR_POS 0 0.90 deg 7 15 deg 1 -75 deg 8 30 deg 2 -60 deg 9 45 deg 3 -45 deg 10 60 deg 4 1.25 sec 12 175 deg 5 -15 deg 12 90 deg 6 0 deg DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 13 20 sec 6 2.0 sec 4 3.0 sec 14 30 sec 7 2.5 sec 15 60 sec DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 60 sec 1 0.5 sec 9 20 sec 14 30 sec 7 2.5 sec 15 60 sec DURATION 0 0.5 sec 4 3.0 sec 8 15 sec 12 60 sec 1 0.5 sec 9 20 sec 13 90 sec 1 0.5 sec 9 20 sec 13 90 sec 1 0.5 sec 9 20 sec 13 90 sec 1 1.0 sec 5 4.0 sec 9 20 sec 13 90 sec 2 1.5 sec 6 5.0 sec 10 30 sec 14 2 min		•				4	50%	spe	ed in the	12	50%	spe	ed in the
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10 LEGO compatible 7 steps 128 stopped 192 stopped 129 1 193 1 194 2 194						7	100%						
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1.0 300	_					_							
- 2.0 300 · 10 300 10 300 10 300						_							
		2.0 350	,	10 360		- 4	J 366	15	J 111111				

Sound Fx Command

sound fx id file parameters (up to 2 parameters)

id	file	Effect Name	Param 1	Param 2
1	0	Increase Volume		
2	0	Decrease Volume		
3	0	Set Volume		VOLUME
4	•	Play Once	RETRIGGER	RELVOLUME
5	•	Play Continuous		RELVOLUME
6	•	Play N Times	REPEAT_COUNT	RELVOLUME
7	•	Play for Duration	DURATION	RELVOLUME
8	•	Motor Pitch Modulated	MOTOR_OUTPUT	GAIN
9	0	Gated Motor Modulated	MOTOR_OUTPUT	GAIN
10	•	Amplitude Motor Modulated	MOTOR_OUTPUT	GAIN
11	•	Stop		
12	0	Play Indexed by Motor Speed	MOTOR_OUTPUT	IDX_OPTIONS
13	•	Random Playback	PROBABILITY	

TIME_MSB

TIME_MSB

TIME_LSB

TIME_LSB

Sound Fx which do not require a *file* specification should substitute a placeholder value of 0:

Set the volume to 60 with fx command sound fx 3 0 0 60

Seek within file playback

Scrub file playback

15

file can be specified either as numeric file ID or string:

Play a sound file randomly
sound fx 13 "Siren1.wav" 3 0
sound fx 13 50 3 0

VOLUME	REL_VOLUM	E	DURATION
0 ~ 255 Volume range	0 0 dB	8 -8 dB	0 0.5 sec 8 15 sec
	1 1 dB	9 -7 dB	1 1.0 sec 9 20 sec
REPEAT_COUNT	2 +2 dB	10 -6 dB	2 1.5 sec 10 30 sec
1 ~ 100 Playback times	3 +3 dB	11 -5 dB	3 2.0 sec 11 45 sec
	4 +4 dB	12 -4 dB	4 3.0 sec 12 60 sec
RETRIGGER	5 +5 dB	13 -3 dB	5 4.0 sec 13 90 sec
No, toggle playback	6 +6 dB	14 -2 dB	6 5.0 sec 14 2 min
 Yes, restart playback 	7 +7 dB	15 -1 dB	7 10 sec 15 5 min
MATAR AUTRUT		PD0010117/	
MOTOR_OUTPUT		PROBABILITY	GAIN
	Current Speed	0 Rare	−100 ~ +100 Gain range
• .	Current Speed	1 Occasionally	
· ·	Current Speed	2 Often	
3 D Target Speed 7 D (Current Speed	3 Very Often	
IDX_OPTIONS			
bit positi	on 7 6 5 4	4 3 2 1 0	
STARTUP OVER	IDE PLAY ST	ARTUP/SHUTDOWN	VOL MODULATION
0 No		10	0 None
1 Yes	1 Y	'es	1 Min
			2 Med
			3 Max
TIME_MSB TIME_LSB			
Combined as a 16 bit two's c	omplement value	e of 100 ms per LSB.	
TIME_MSB TIME_	LSB	TIME_MSB T	IME_LSB
0x7F 0	- xFF 3276.7 se	ec 0xFF	0xFF -0.1 sec
		0xFF	0xFE -0.2 sec
0×00 0	x 01 0.1 sec		
0×00 0	x00 0 sec	0×80	0x00 -3276.8 sec

Directional Headlight for a Train

```
# Front light: Ch 1
# Rear light: Ch 2
# odd numbered light channels ON when Fwd
# even numbered light channels ON when Rev
# method 1: use one startup action with
# Light On/Off toggle with DIR_OPTIONS
event startup 1 {
  light [1, 2] fx 1 9
# method 2: use two startup actions
# (one for each group of light channels)
# configured as Status Indicators with
# bits 0 and 1 of SOURCE2
event startup 1 {
  light 1 fx 18 0 1
event startup 2 {
 light 2 fx 18 0 2
```

Locomotive Ditch Lights

```
# Setup ditch lights which stay ON between
# flashing intervals
# 5 = 1.25 sec period
# 6 = 25% fade
# 8 = 40% duty cycle
# 0x03 = channels 1 & 2
# 1 = transition to stay ON

event startup 1 {
    light all fx 11 5 6 8 0x03 1
}
# Same as above, but flashing lasts 10 sec
# 0x73 = transition to timed 10sec duration
event startup 1 {
    light all fx 11 5 6 8 0x03 0x73
}
```

Bluetooth Connection Indicator Light

```
event ble connect {
  light 1 on
}
event ble disconnect {
  light 1 off
}
```

Bluetooth Connection Indicator with IR disable

```
event ble connect {
   light 1 on
   ir off
}
event ble disconnect {
   light 1 off
   ir on
}
```

Bluetooth Activity Indicator Light # Setup Status Indicator Light

```
# action using bit 6 of SOURCE1
light 1 fx 18 0x40 0x00
# Can also assign this to a startup action
event startup 1 {
   light 1 fx 18 0x40 0x00
```

USB Activity Indicator Light

```
# Setup Status Indicator light
# action using bit 1 of SOURCE1
```

light 1 fx 18 0x02 0x00

Sound Playback with Bargraph Lights

```
# Setup Status Indicator light
# action using bit 1 of SOURCE1
# 0 = L to R bar graph
# 6 = 25% fade factor
# 0 = use 8 light channels

light all fx 10 0 6 0
sound play "MusicClip.wav"
wait sound "MusicClip.wav"
light all off
```

Joystick activated Crossing Lights / Arm

```
# Configure crossing lights which flash
# ch 1 and 2
# activate a crossing arm attached to servo
# motor
# Use joystick Ch 1 left lever to toggle

event joy ch 1 left up {
    light all fx 11 5 6 8 0x03
    motor servo 90
}
event joy ch 1 left down {
    light [1, 2] off
    motor servo 0
}
```

Stop Motor when BLE Disconnects

```
event ble disconnect {
  motor off off
}
```

Toggle Lights with touchLAB

```
event button {
   light 1 fx 1
}
```

Show touchLAB button status with a Light

```
# Method 1: setup events to respond to
# up and down event separately

event button up {
    light 1 on
}
event button down {
    light 1 off
}

# Method 2: setup a Status Indicator light
# action using bit 6 of SOURCE2

light 1 fx 18 0x00 0x40

# Can also assign this to a startup action
event startup 1 {
    light 1 fx 18 0x00 0x40
}
```